

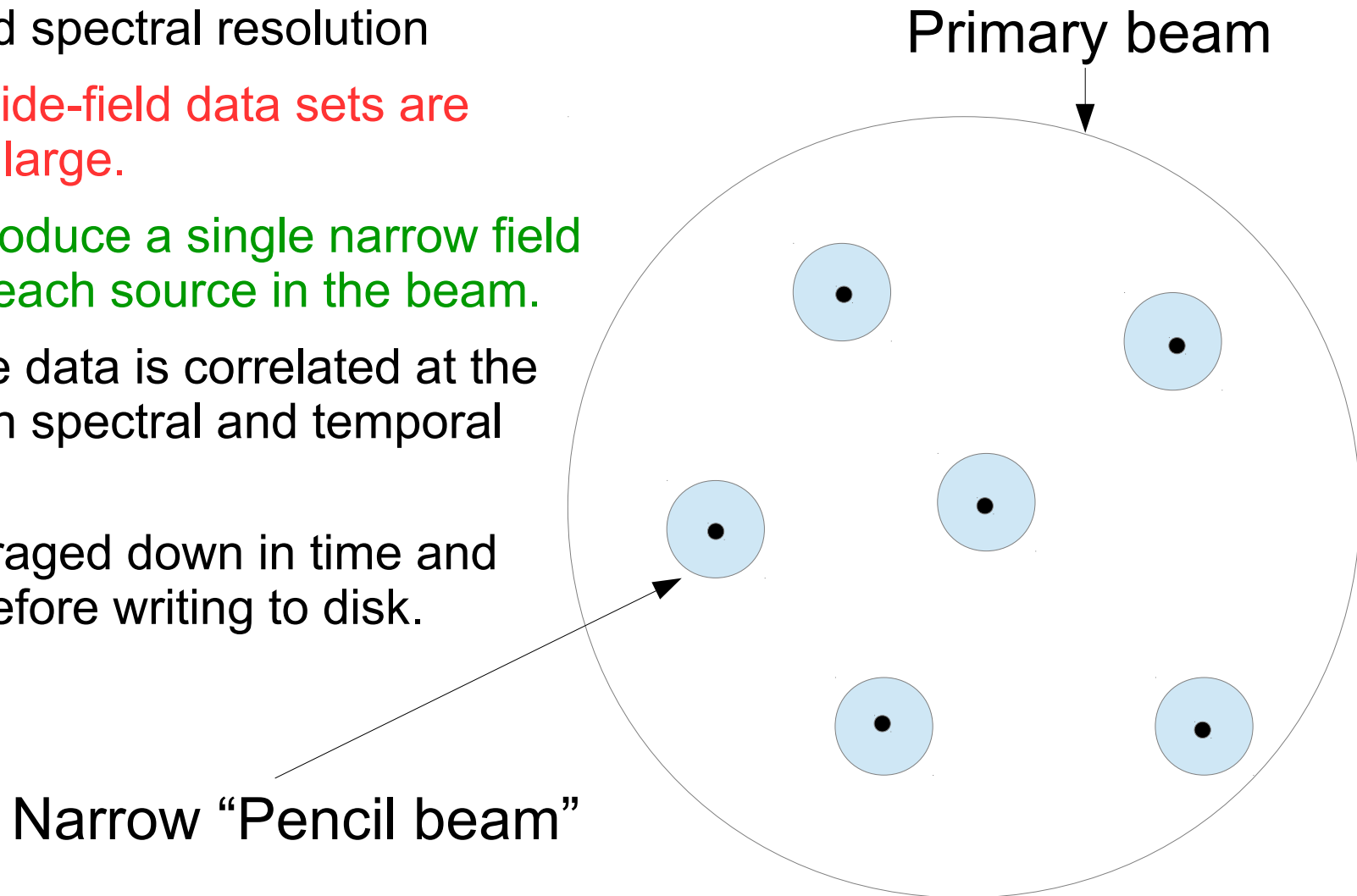
# Beam shapes for calibrating off-axis detections

Aard Keimpema (JIVE)

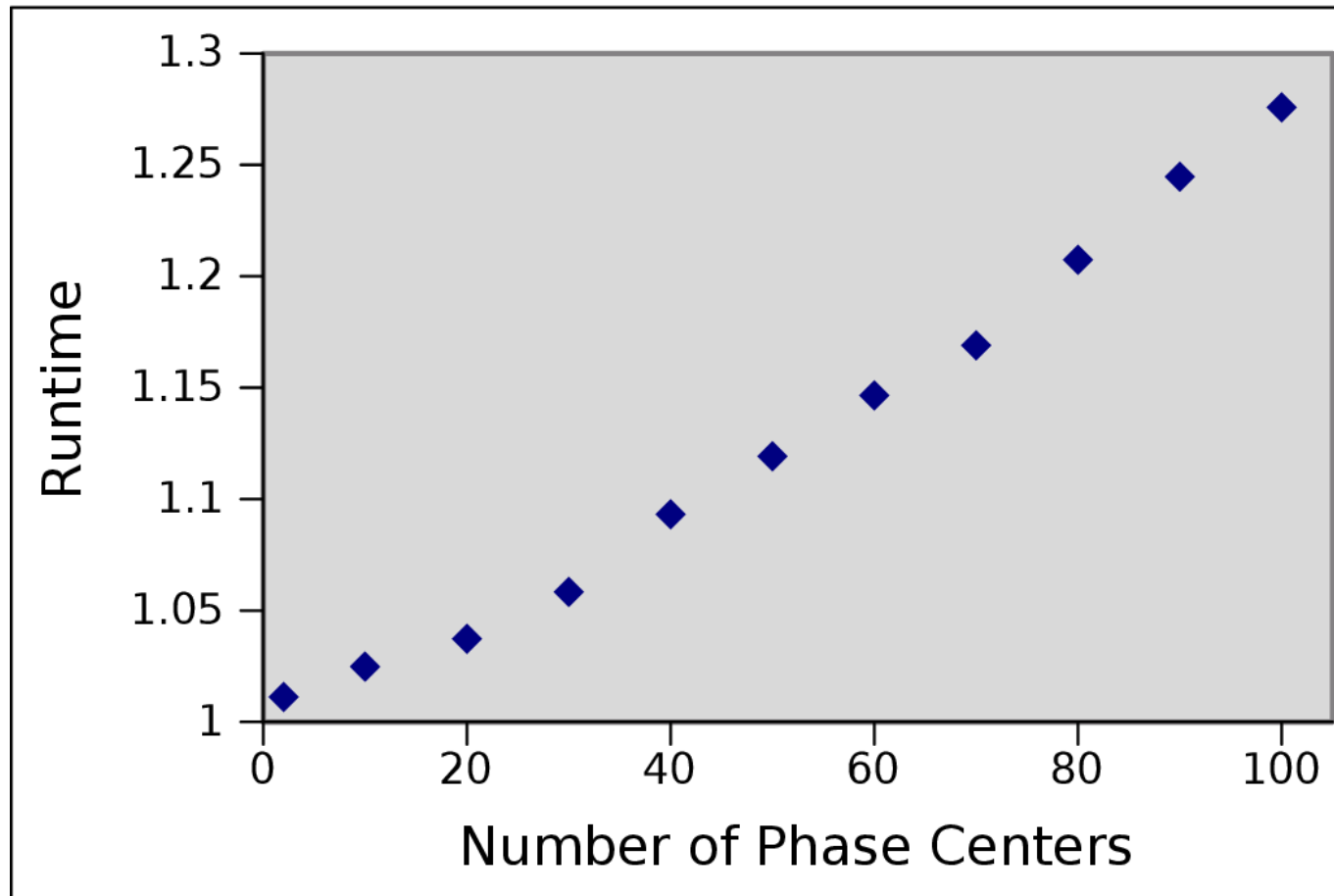
*keimpema@jive.nl*

# Multiple simultaneous phase centers

- An interferometer can map the entire primary antenna beams as long as the data is correlated with sufficient temporal and spectral resolution
- **Problem : Wide-field data sets are prohibitively large.**
- **Solution : Produce a single narrow field data set for each source in the beam.**
- Internally the data is correlated at the required high spectral and temporal resolution.
- Results averaged down in time and frequency before writing to disk.



# Multiple simultaneous phase centers



Going from 2 to 100 sources requires only  
30% more correlation time!

# Airy Disk Beam Model

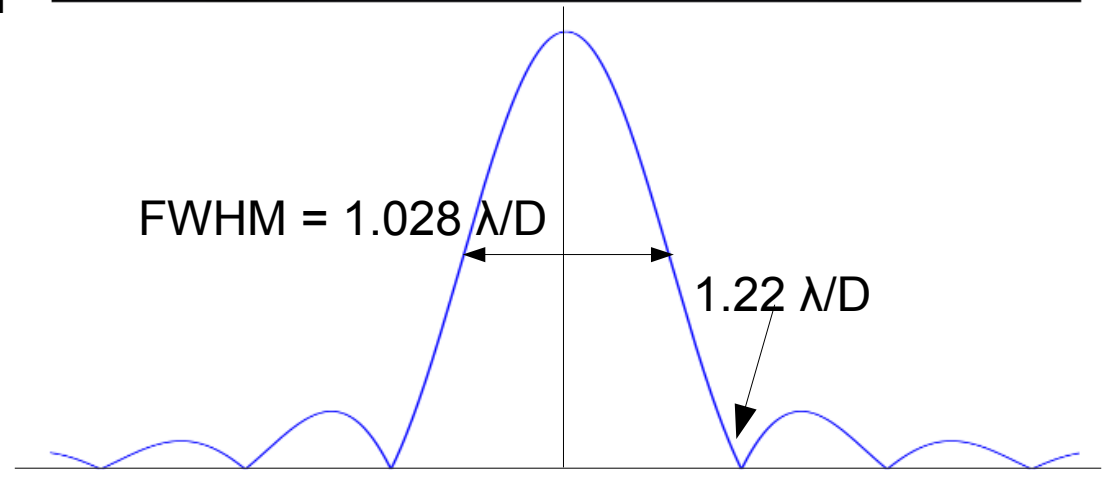
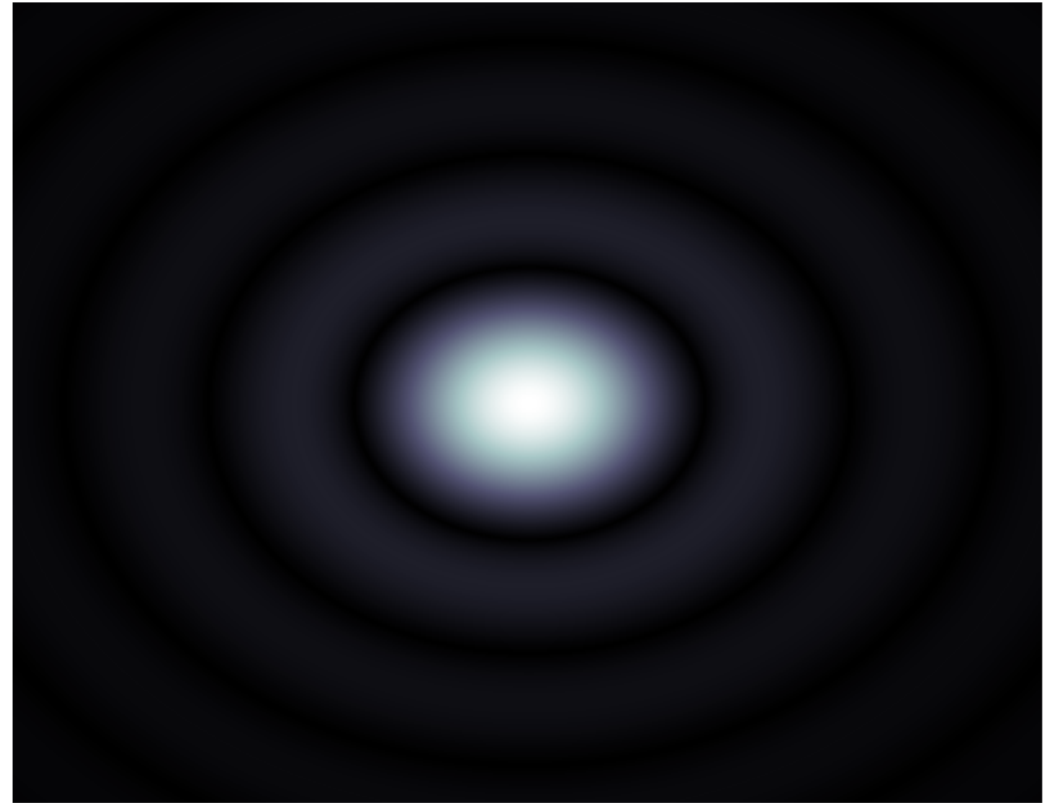
First order model : Uniformly illuminated circular aperture (Airy Disk)

$$I(\theta) = \left| \frac{2J_1(z)}{z} \right|^2, \quad z = \frac{\pi D}{\lambda} \sin(\theta)$$

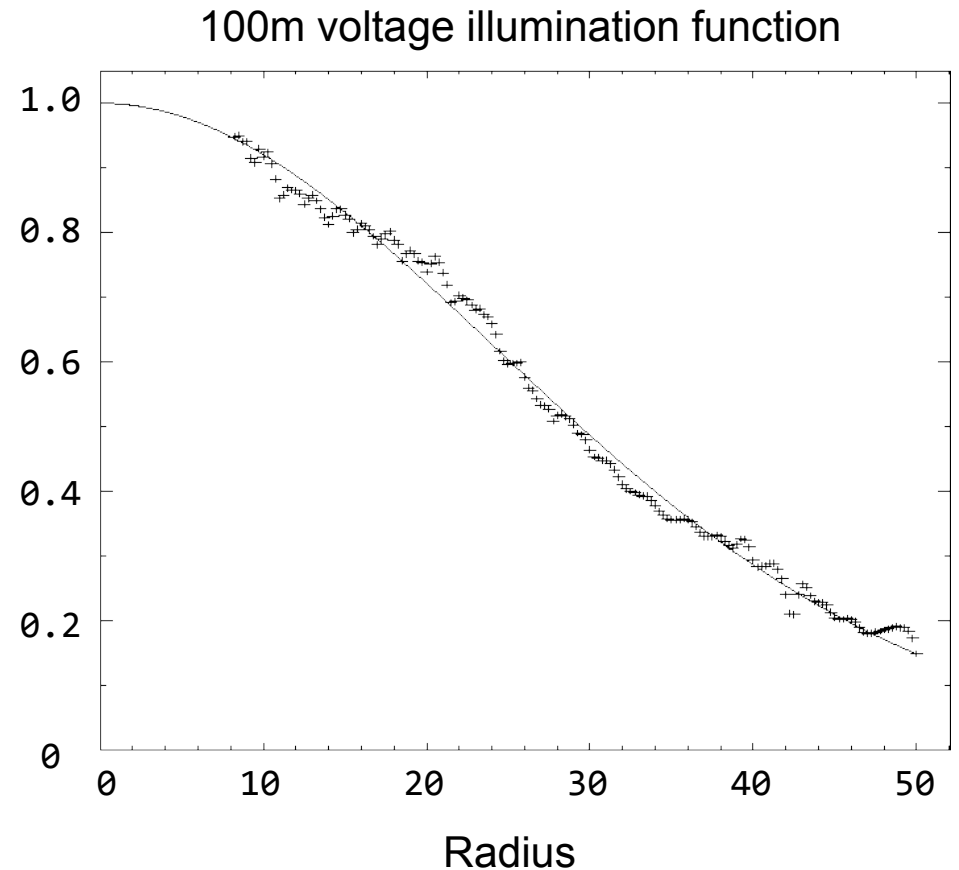
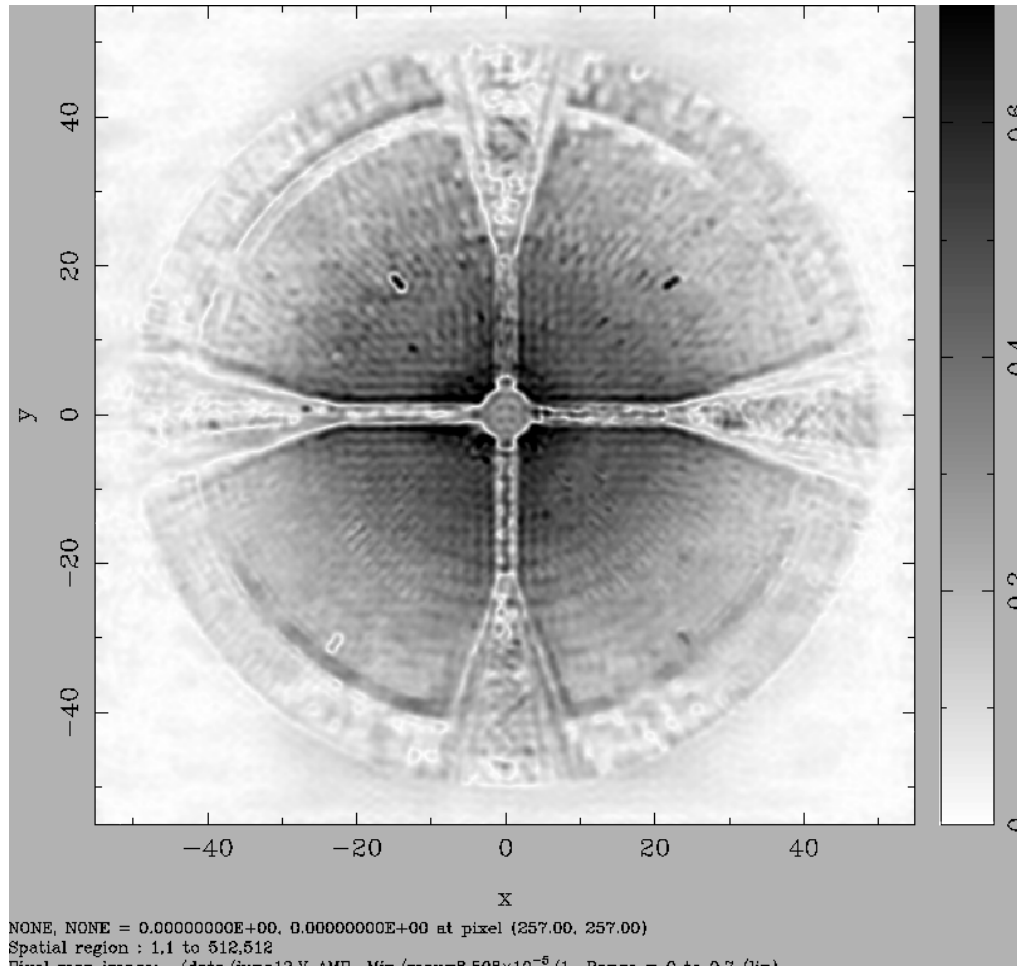
$D$  = Dish diameter,

$\lambda$  = wavelength

$J_1(z)$  = Bessel function of the first kind



# Effelsberg illumination pattern @11.7 Ghz



# The Effelsberg Holography Campaign - 2001

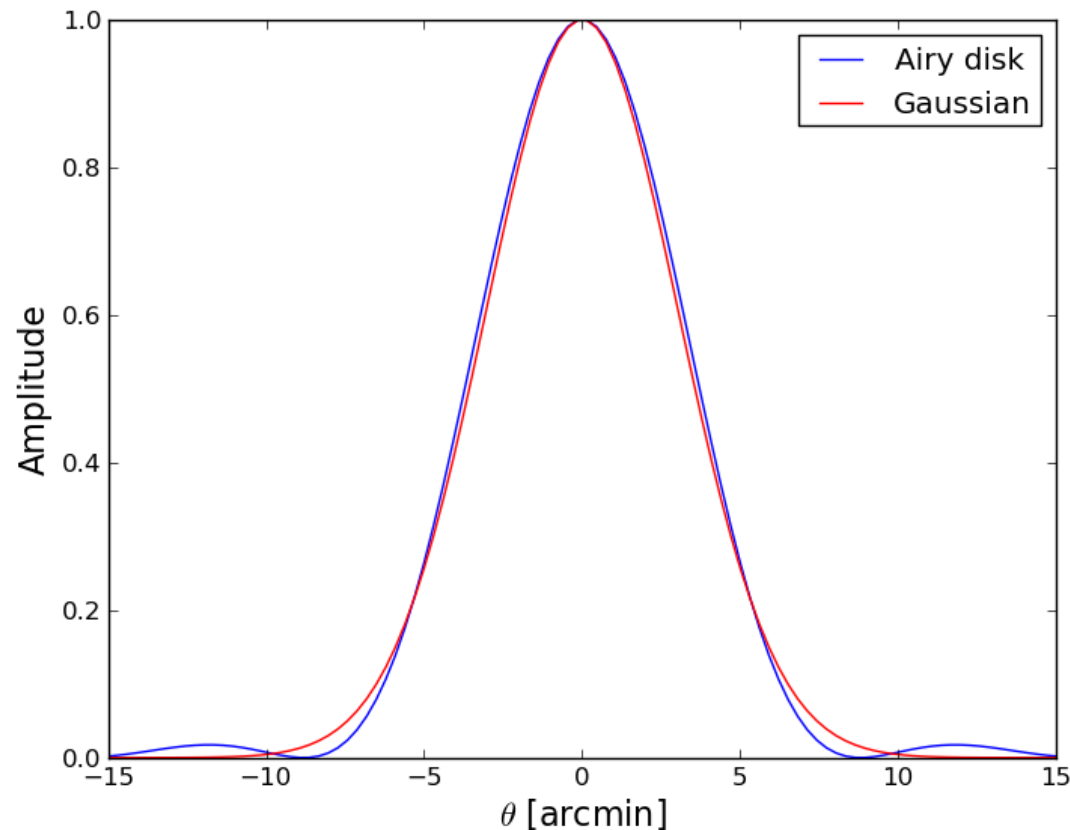
*M.Kesteven, D.Graham, E.Fürst, O.Lochner & J.Neidhöfer*

# Gaussian model

- The Airy disk model can very closely be approximated by a Gaussian model

$$I(\theta) = A_0 e^{-\frac{\theta^2}{2\sigma^2}}$$

- The optimum fit is  $\sigma = 0.42\lambda/D$ , for apperture of width D



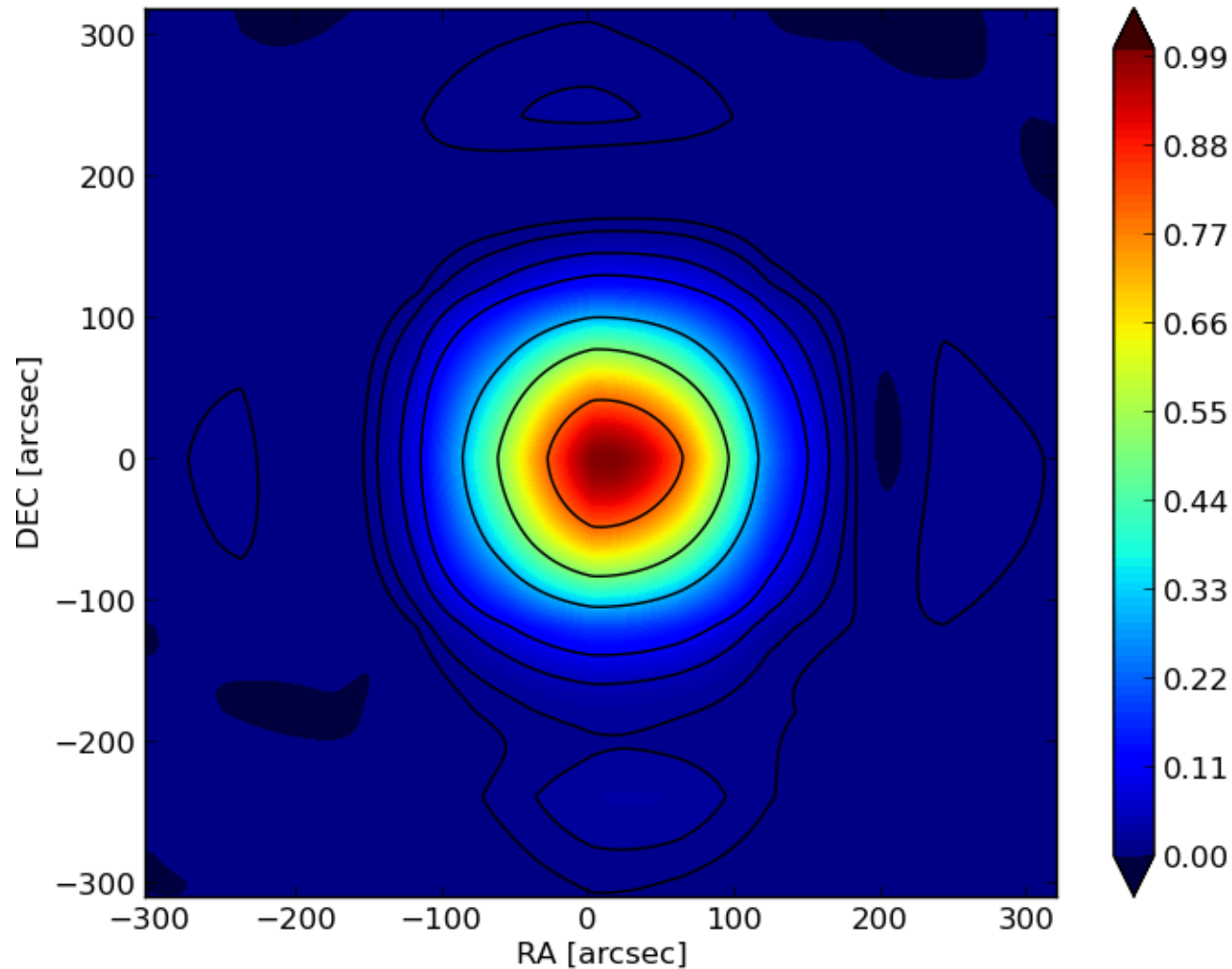
# Model fitting beam shapes

- Least-squares fitting : For a dataset  $\mathbf{d}$ , containing N data points sampled at positions  $\mathbf{r} = r_0, r_1, \dots, r_{N-1}$  and model given by the function  $f(\mathbf{r}; \mathbf{p})$  find a set of parameters  $\mathbf{p}$  that minimizes

$$\chi^2 = \frac{\sum_i |f(\mathbf{r}_i; \mathbf{p}) - d_i|^2}{\sigma^2}$$

- Python program was developed that fits a given beam map to a particular model using least squares fitting.
- Beam map is read from FITS file, other data formats can easily be supported. Can handle multiple input files.
- Supports Gaussian and Airy disk beam models for fitting. Very easy to add new beam models
- Algorithm**
  - 1) Make initial estimate of model parameters
  - 2) Box data, restrict model fitting to data points inside beam
  - 3) Least squares fit beam model to data using the Levenberg–Marquardt algorithm.
  - 4) Reapply steps 2) and 3) using new model parameters

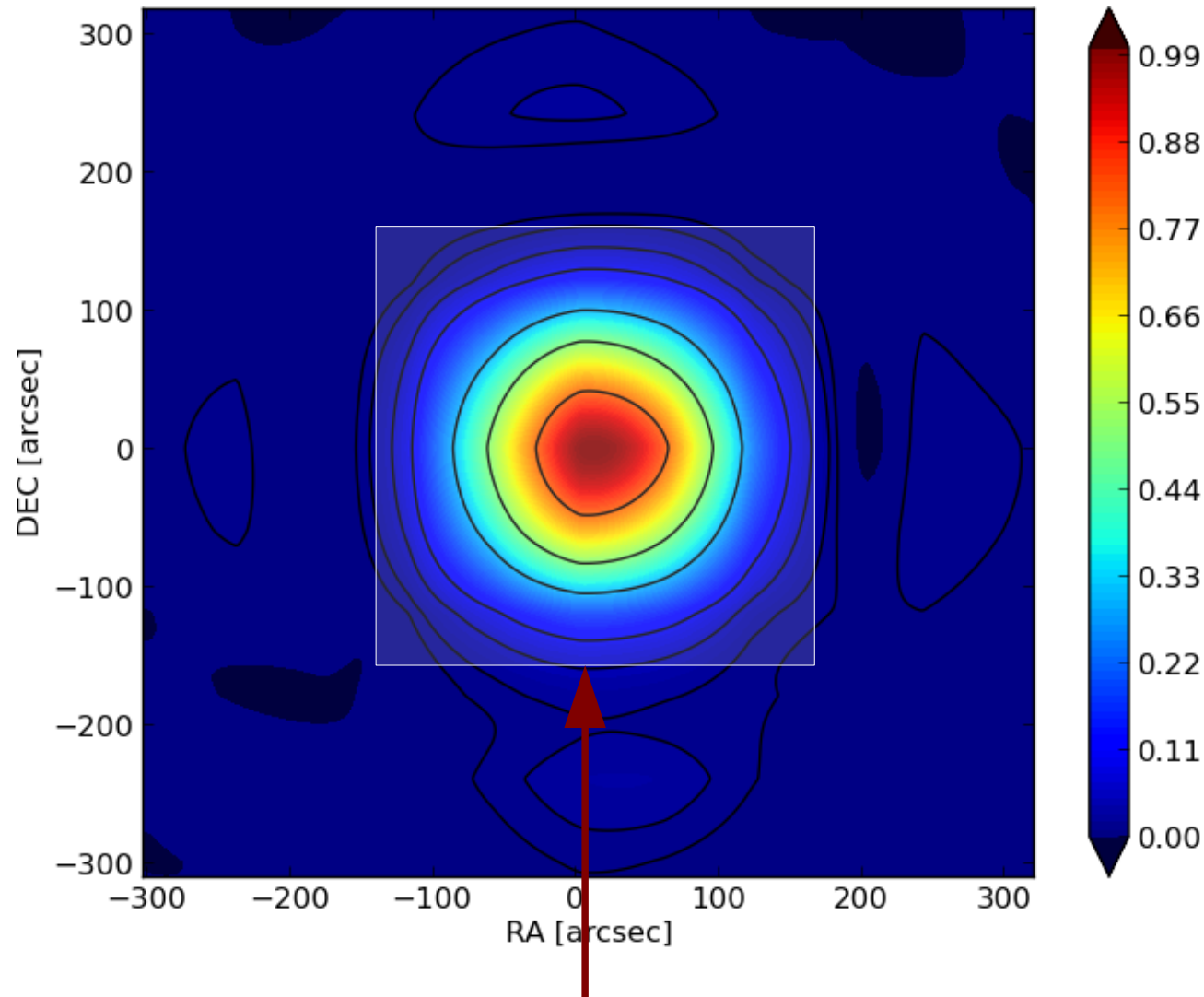
# Effelsberg map of 3C48 @ 4.85GHz



Original map 750 x 450 points (not all shown)  
2" resolution, 160 x 160 data points within beam.  
Note the rectangular features at the primary beam edge



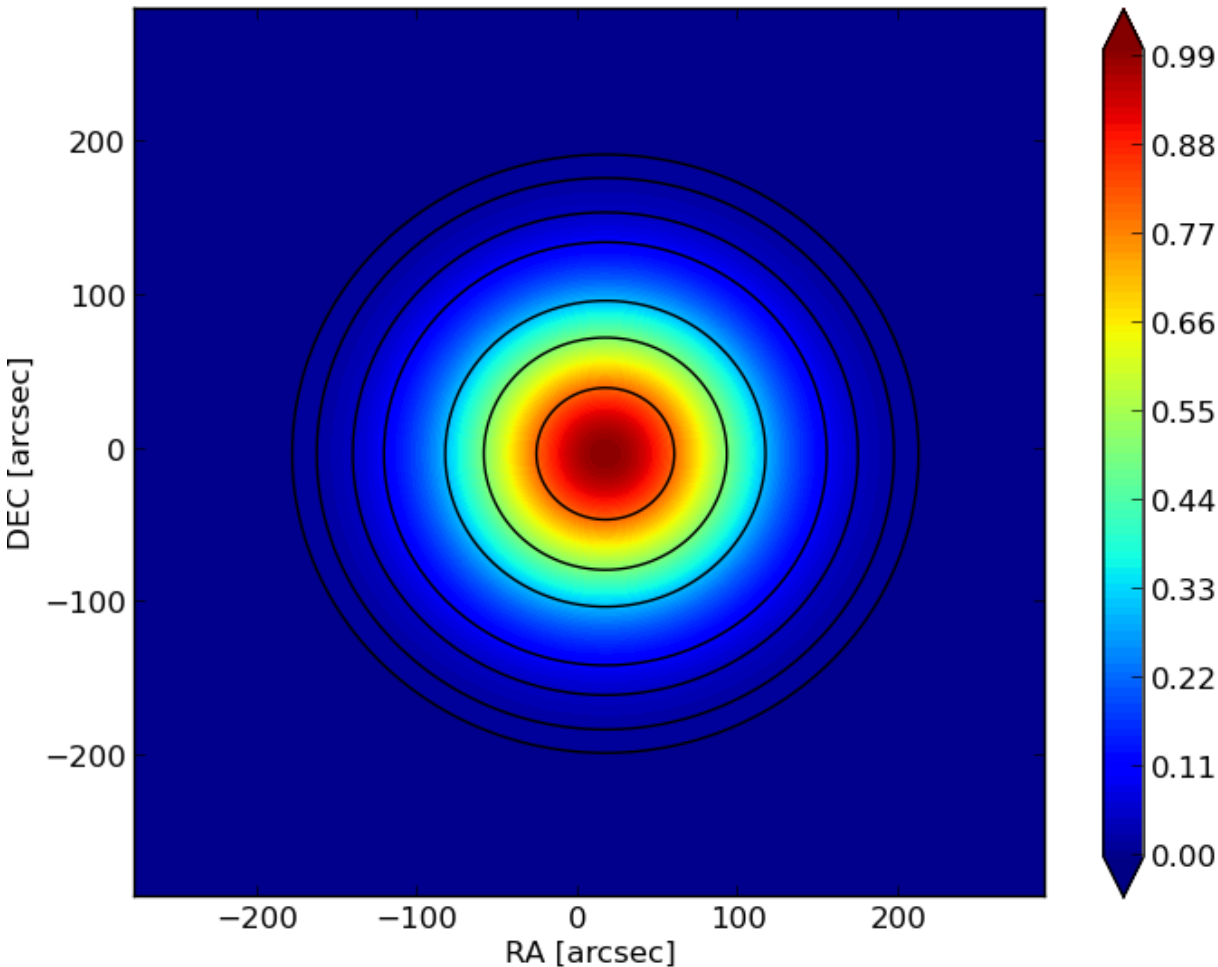
# Effelsberg map of 3C48 @ 4.85GHz



Before model fitting we box the data, only these point are used in the fit

# Gaussian model fit

$$\text{Model: } I(x, y) = A_0 e^{-\frac{(x-x_0)^2 + (y-y_0)^2}{2(z\lambda)^2}}$$



## Results

$$A_0 = 1.457\text{e}+04 \pm 5.14\text{e}+00$$

$$X_0 = 1.663\text{e}+01 \pm 2.26\text{e}-02$$

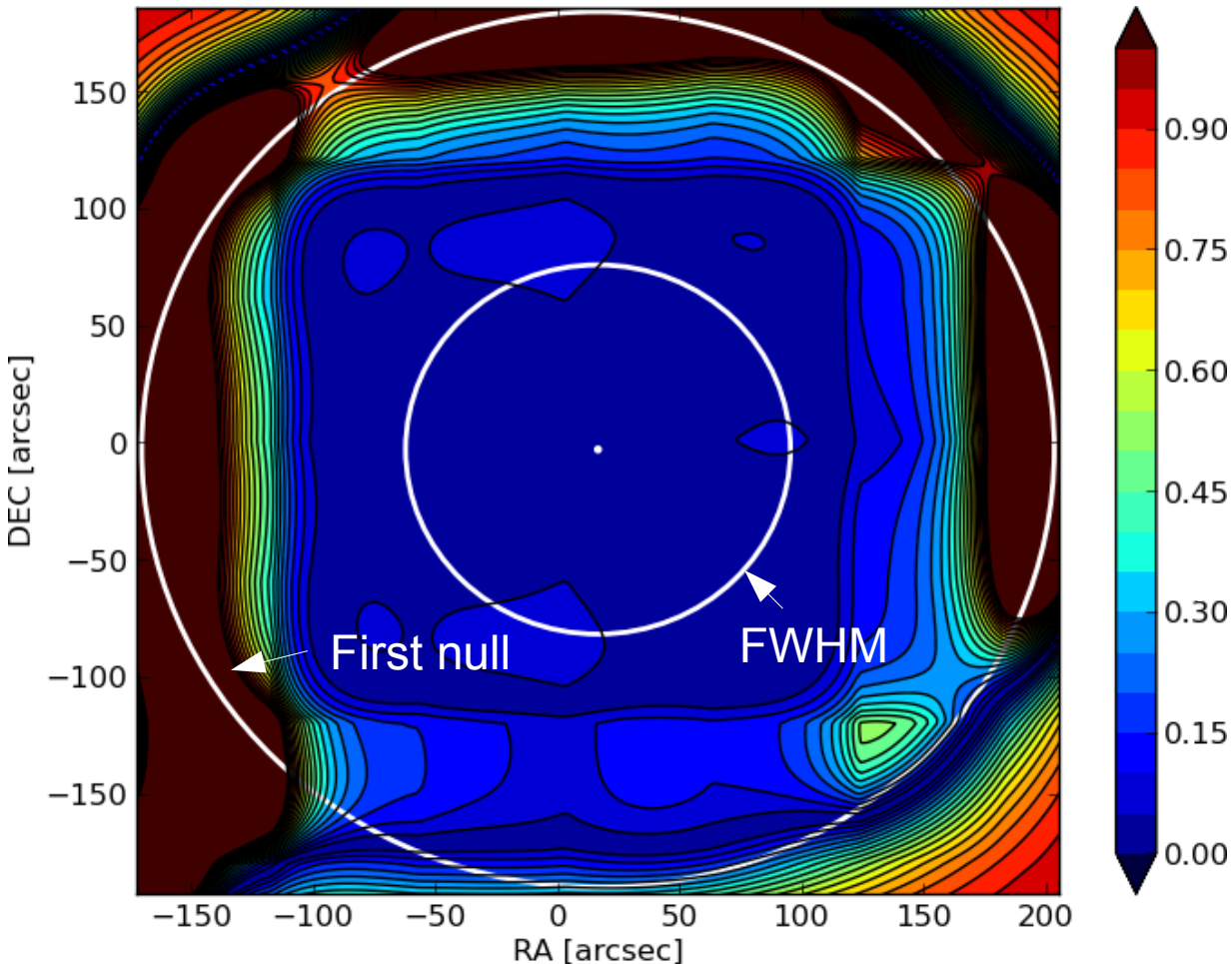
$$y_0 = -3.053\text{e}+00 \pm 2.26\text{e}-02$$

$$Z = 1.040\text{e}+03 \pm 2.65\text{e}-01$$

$$\text{FWHM} = 151.6 \text{ arcseconds}$$

# Residuals Gaussian model

$$\text{Model: } I(x, y) = A_0 e^{-\frac{(x-x_0)^2 + (y-y_0)^2}{2(z\lambda)^2}}$$



## Results

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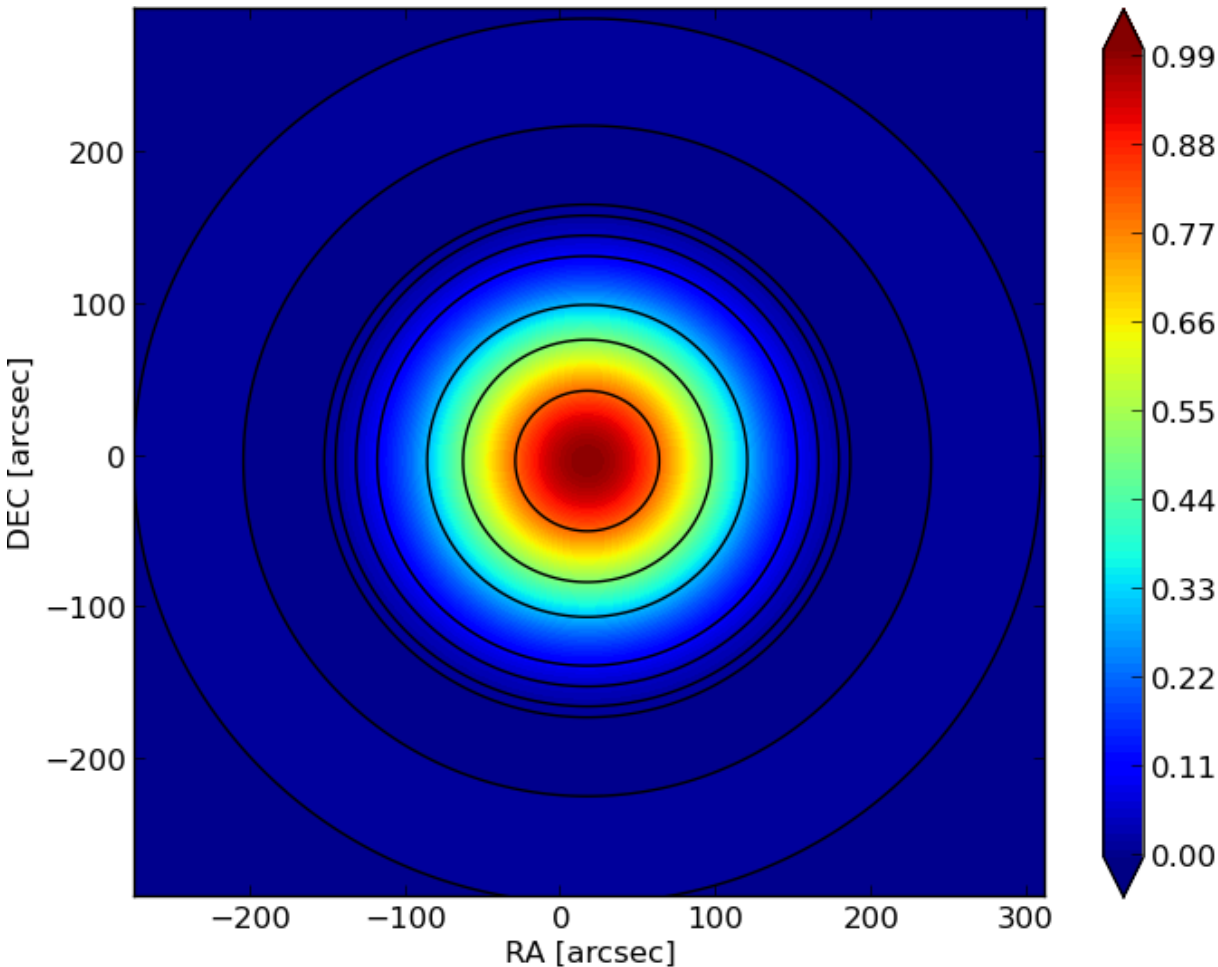
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$$\text{FWHM} = 151.6 \text{ arcseconds}$$

# Airy disk model fit

$$\text{Model: } I(x, y) = A_0 \left| \frac{2 J_1(z)}{z} \right|^2, \quad z = \sqrt{(x - x_0)^2 + (y - y_0)^2} \frac{\pi D}{\lambda}$$



## Results

$$A_0 = 1.3974+04 \pm 3.35e+00$$

$$x_0 = 1.658e+01 \pm 1.60e-02$$

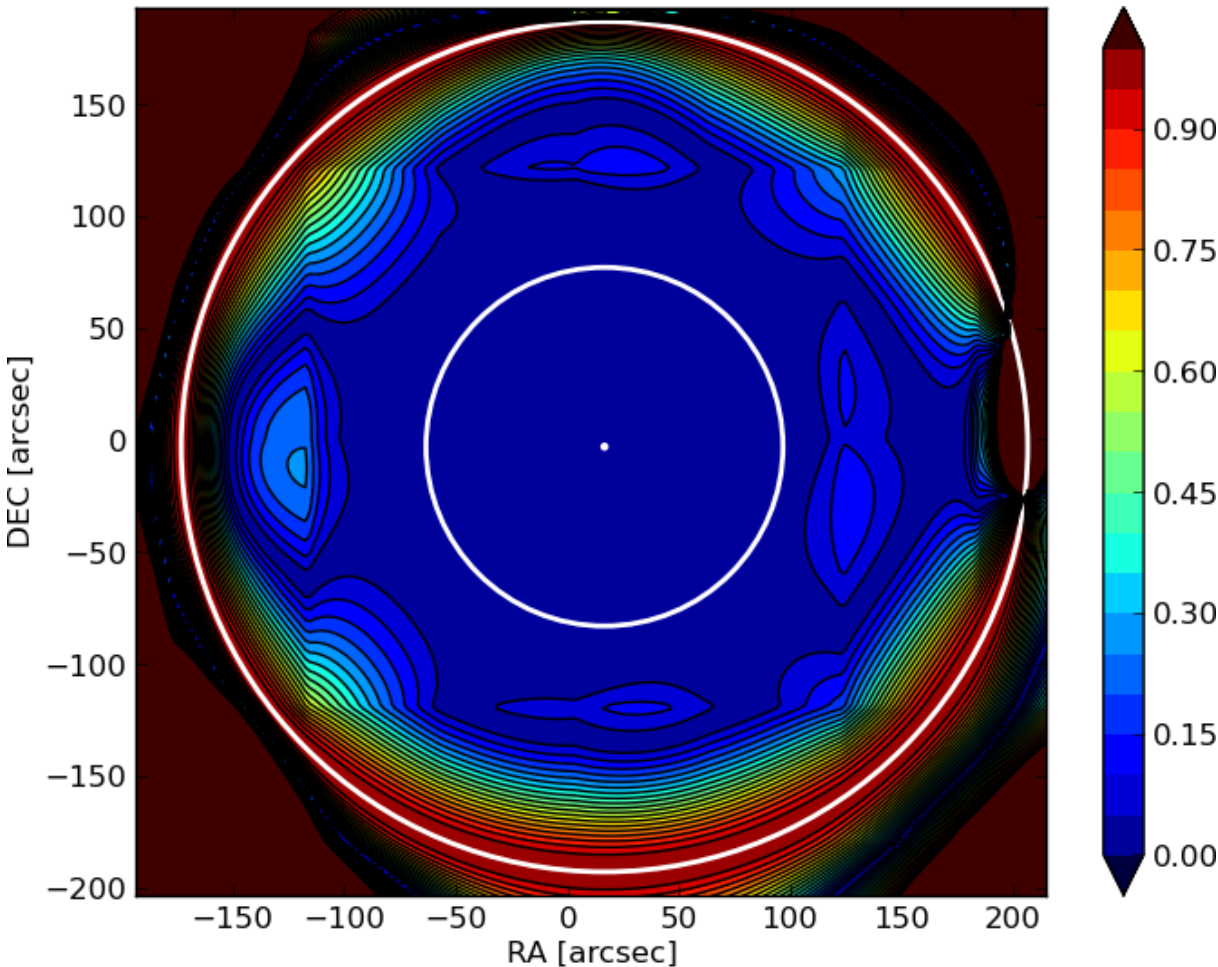
$$y_0 = -3.061e+00 \pm 1.61e-02$$

$$D = 8.200e+01 \pm 1.32e-01$$

$$\text{FWHM} = 160 \text{ arcseconds}$$

# Residuals Airy disk model

$$\text{Model: } I(x, y) = A_0 \left| \frac{2 J_1(z)}{z} \right|^2, \quad z = \sqrt{(x - x_0)^2 + (y - y_0)^2} \frac{\pi D}{\lambda}$$



## Results

$$A_0 = 1.3974+04 \pm 3.35e+00$$

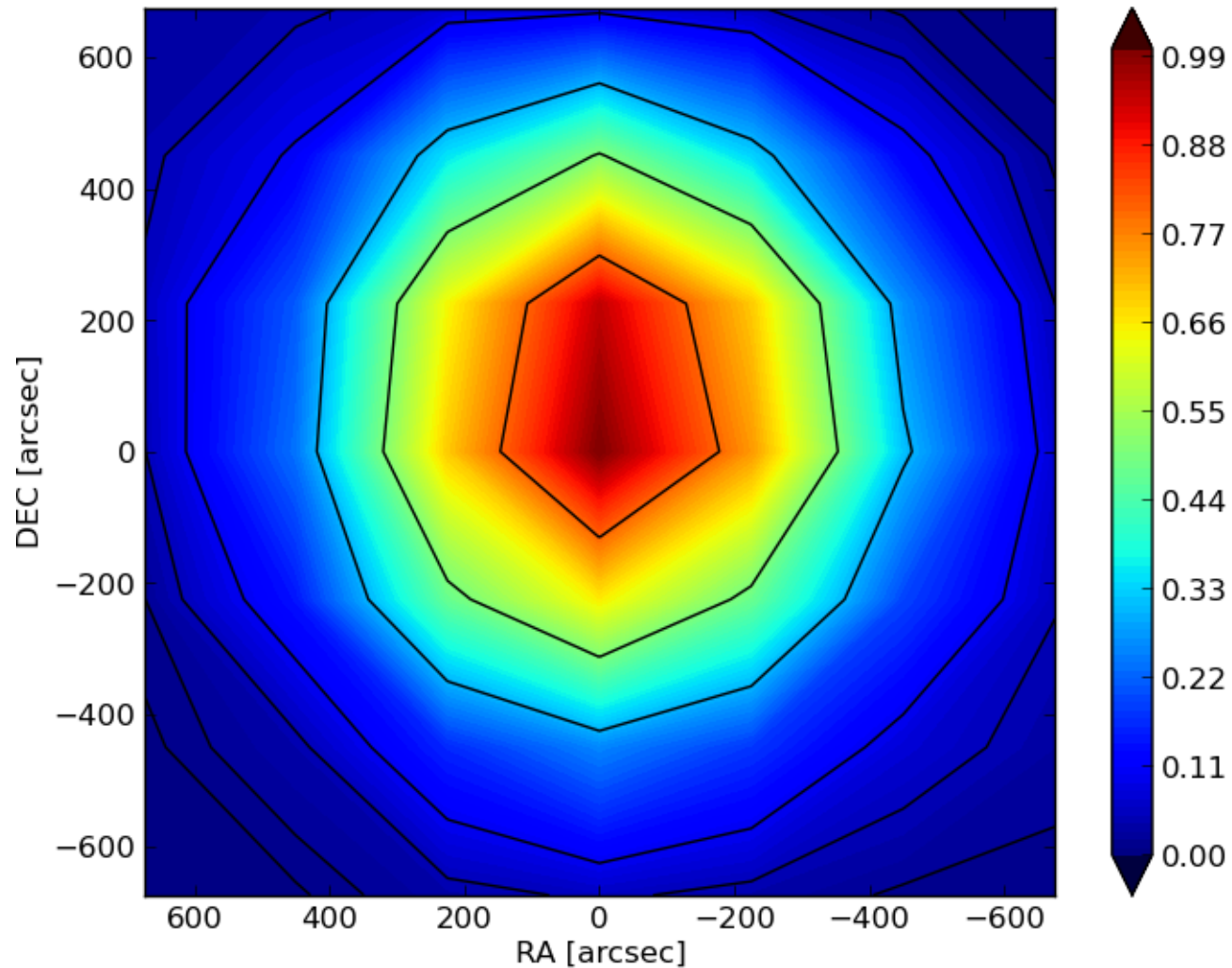
$$x_0 = 1.658e+01 \pm 1.60e-02$$

$$y_0 = -3.061e+00 \pm 1.61e-02$$

$$D = 8.200e+01 \pm 1.32e-01$$

$$\text{FWHM} = 160 \text{ arcseconds}$$

# Onsala map of 3C286 @ 4.6GHz

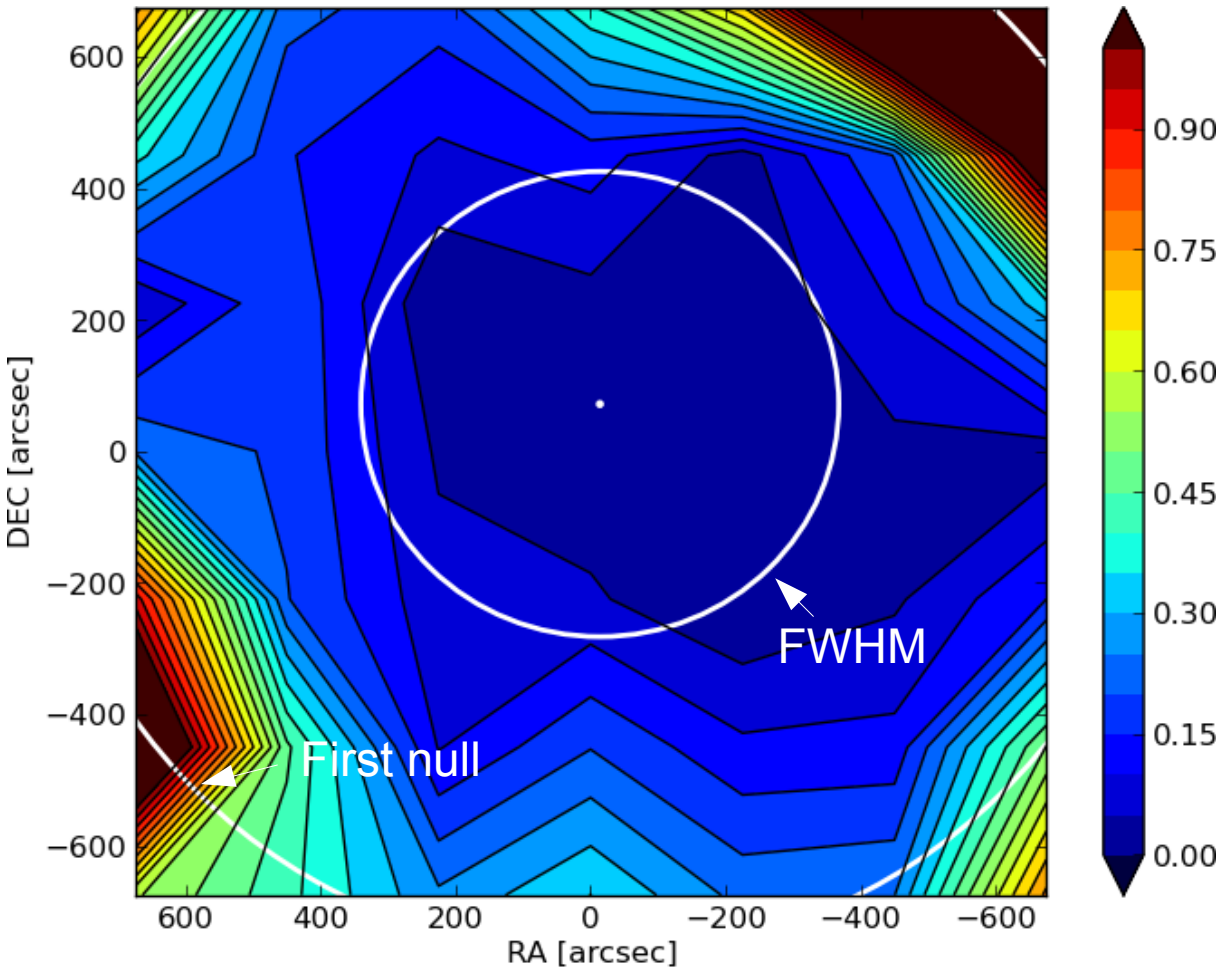


Dataset contains 7 x 7 datapoints (3'40" resolution)  
Each data point is a 800 point spectrum (3.2 MHz Bandwidth)



# Residuals Gaussian model

$$\text{Model: } I(x, y) = A_0 e^{-\frac{(x-x_0)^2 + (y-y_0)^2}{2(z\lambda)^2}}$$



## Results

$$A_0 = 6.178\text{e}+01 \pm 1.19\text{e}+00$$

$$x_0 = -1.378\text{e}+01 \pm 5.46\text{e}+00$$

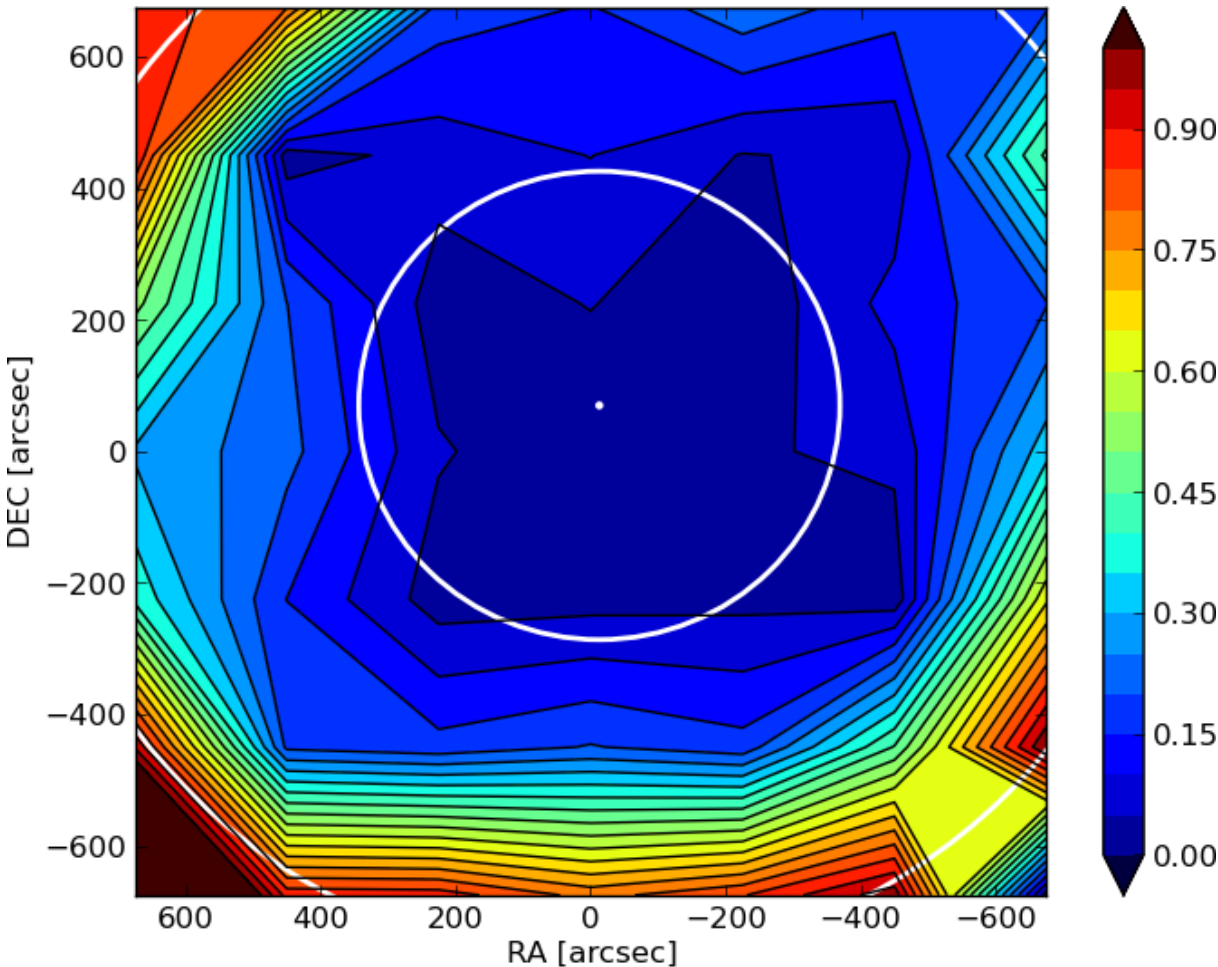
$$y_0 = 7.173\text{e}+01 \pm 5.51\text{e}+00$$

$$Z = 4.428\text{e}+03 \pm 6.53\text{e}+01$$

$$\text{FWHM} = 680 \pm 10 \text{ arcseconds}$$

# Residuals Airy disk model

$$\text{Model: } I(x, y) = A_0 \left| \frac{2 J_1(z)}{z} \right|^2, \quad z = \sqrt{(x - x_0)^2 + (y - y_0)^2} \frac{\pi D}{\lambda}$$



## Results

$$A_0 = 5.961\text{e}+01 \pm 1.05\text{e}+00$$

$$X_0 = -1.300\text{e}+01 \pm 5.19\text{e}+00$$

$$Y_0 = 6.964\text{e}+01 \pm 5.29\text{e}+00$$

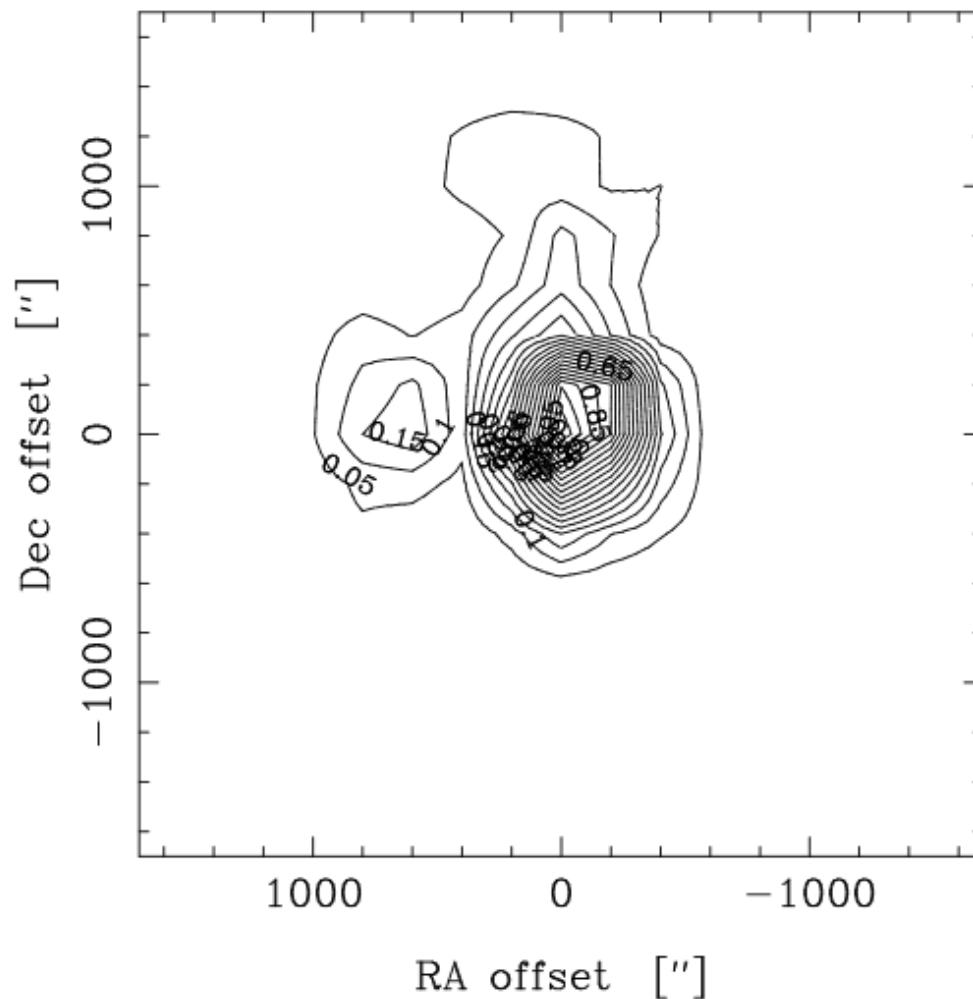
$$D = 1.943\text{e}+01 \pm 2.43\text{e}-01$$

$$\text{FWHM} = 712 \text{ arcseconds}$$



# Observing antenna beams

- Open questions
    - How do beam shapes vary with elevation
- Example : Onsala (6.7 Ghz) at low elevation*



# Observing antenna beams

- Open questions
  - How do beam shapes vary with elevation
  - Beam offsets between polarizations
  - Dependence on frequency
  - Are polynomial model feasible?
- Only beam information up to the first null is used in the fit. But we need some data points further out to determine bias.
- Integration times should be long enough to average out RFI
- Cover range of elevations but most structure is expected at lower elevations. Eg.  $80^\circ$ ,  $60^\circ$ ,  $40^\circ$ ,  $20^\circ$ ,  $10^\circ$
- Would even lower elevations be possible?
- How much elevation change is expected during the observation of a single map? Small enough to treat it as constant?